# Stochastic parameterization: is sophistication useful?

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# A practical view

- Near-grid scale in GCM and NWP models is not energetic enough
- Adding near-grid scale noise can correct that
- Some very simple noise generators are beneficial multiplicative or random-parameters noise in NWP ensembles
- Are complex methods based on a rethought parameterization strategy necessary or useful in practice?
- i.e., what physical constraints should control the character of the stochastic tendencies?



# **Scales for parameterization**

Three important scales to consider:

- 1. intrinsic scale of the process to be parameterized (turbulent eddy sizes, cloud dimensions...)
- 2. a large-scale, sufficient to contain many instances of the process

i.e., scale at which time average pprox space average pproxensemble average

3. the model grid box size



mental air. A cloud which has lost buoyancy is shown detraining cloud air into the environment.



# **Parameterization strategy**

Is a function of the grid scale



- Determinstic parameterization
- Good scale separation: fluctuations small on scale  $\Delta x$
- Parameterized process is a function of current state of grid box



# **Parameterization strategy**



- Stochastic parameterization
- Parameterized process is a function of large-scale state
- Grid-box state  $\neq$  large-scale state space average over  $\Delta x \neq$  ensemble average
- Process as realized on grid-box scale is a sub-sampling of the full ensemble so fluctuations important



# Plant and Craig parameterization

- Deep convection scheme, explicitly designed to be stochastic following this conceptual framework
- Number of cumulus clouds  $\langle N \rangle$  in GCM grid box need not be large
- Mass-flux formalism with spectrum of plumes of varying sizes
- Select a random sample of plumes
- Stochastic part of  $\partial_t X \sim \sqrt{\langle N \rangle}$
- $\bullet$  cf. multiplicative noise in which it  $\sim \langle N 
  angle$



### **Example pdf of mass flux**



- p(M) produced by Plant-Craig scheme, over area (64km)<sup>2</sup>
- 3D simulation of radiative-convective equilibrium at  $\Delta x = 32$ km
- Agrees with theory and CRM results



# Simple additive noise good enough



- Perturbations in boundary-layer  $\theta$  alter triggering and displace storms
- Can produce ensemble rainfall spread similar to ensembles representing parameter/structural uncertainty



### **Framework of tests**

Single-column tests for tropical west-Pacific warm pool, based on TOGA-COARE

- 39-member ensembles used
- includes small initial condition perturbations to boundary-layer temperature
- different random number seed for the stochastic method in each run
- vary the character of multiplicative noise, and compare with Plant-Craig



# **Multiplicative noise**

Apply multiplicative noise to one scheme only



Dotted: IC, Black: all, Red: radiation, Green: boundary layer, Purple: convection, Blue: large-scale cloud

- Similar vertical profiles of spread
- Model propagates uncertainty: perturbing one scheme induces noise in input to the next
- Spread from perturbing any one scheme  $\sim 70\%$  spread from 4 schemes together



# T/q correlations

• Decorrelate multiplicative noise to  $\partial_t T$  and  $\partial_t q$ 



- Unphysical spread beyond 18th: stronger than with quenched random numbers
- Decorrelated noise violates energy conservation,  $L\Delta q \neq C_p \Delta T$  when a cloud condenses/evaporates



# **Sampling uncertainty**

 Spread in column-average T from Plant-Craig as function of grid-box size



Similar to mult. noise or random parameters for  $\Delta x = 50$ km



### **Stochastic drift**

• Effect of noise on mean-state with Plant-Craig



- Ensemble mean T difference: Plant-Craig at  $\Delta x = 50$ km
  - Plant-Craig deterministic
- Stochastic drift almost like having a different parameterisation



# Conclusions

- Simple additive or multiplicative noise source sufficient for some purposes
- i.e., can use generic method and may not be necessary to address all sources of GCM uncertainty
- But some physical constraints are necessary e.g.  $L\Delta q = C_p \Delta T$  when cloud condenses/evaporates is useful to know
- Parameterization strategy properly depends on intrinsic scales and on  $\Delta x$
- For deep convection, cloud-sampling uncertainty becomes as important as the uncertainty in representing a cloud at  $\Delta x \sim 50$  km
- An explicitly stochastic parameterization scheme is then required

