

Representation of model error in a convective-scale ensemble

Ross Bannister^{^*}, Stefano Migliorini^{^*}, Laura Baker^{*}, Ali Rudd^{*†}

[^] National Centre for Earth Observation

^{*} DIAMET, Dept of Meteorology, University of Reading

[†] Now NERC Centre for Ecology and Hydrology, Wallingford

With thanks to Ian Boutle, Jonathan Wilkinson, Jean-Francois Caron, Neil Bowler, Emilie Carter, Giovanni Leoncini, David Simonin, Simon Wilson, Sue Ballard
Met Office and Monsoon computing facilities

Data assimilation (DA) allows information to be squeezed from EO data



NWP increasingly relies on EO data



But, DA must be formulated carefully, inc well characterised forecast error statistics



Information from an ensemble can provide information about forecast error statistics



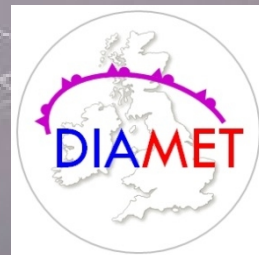
Study a convective-scale ensemble problem



How to generate an appropriately spread ensemble



What useful things can we learn from this ensemble?



What can we learn from forecast ensembles?

USING AN ENSEMBLE

Forecast uncertainty and meteorological understanding

- All forecasts are wrong – forecast uncertainty assessment.
- Data assimilation – how to interpret a-priori information.
- How are (errors in) forecast fields correlated?



Uncertainty information is important

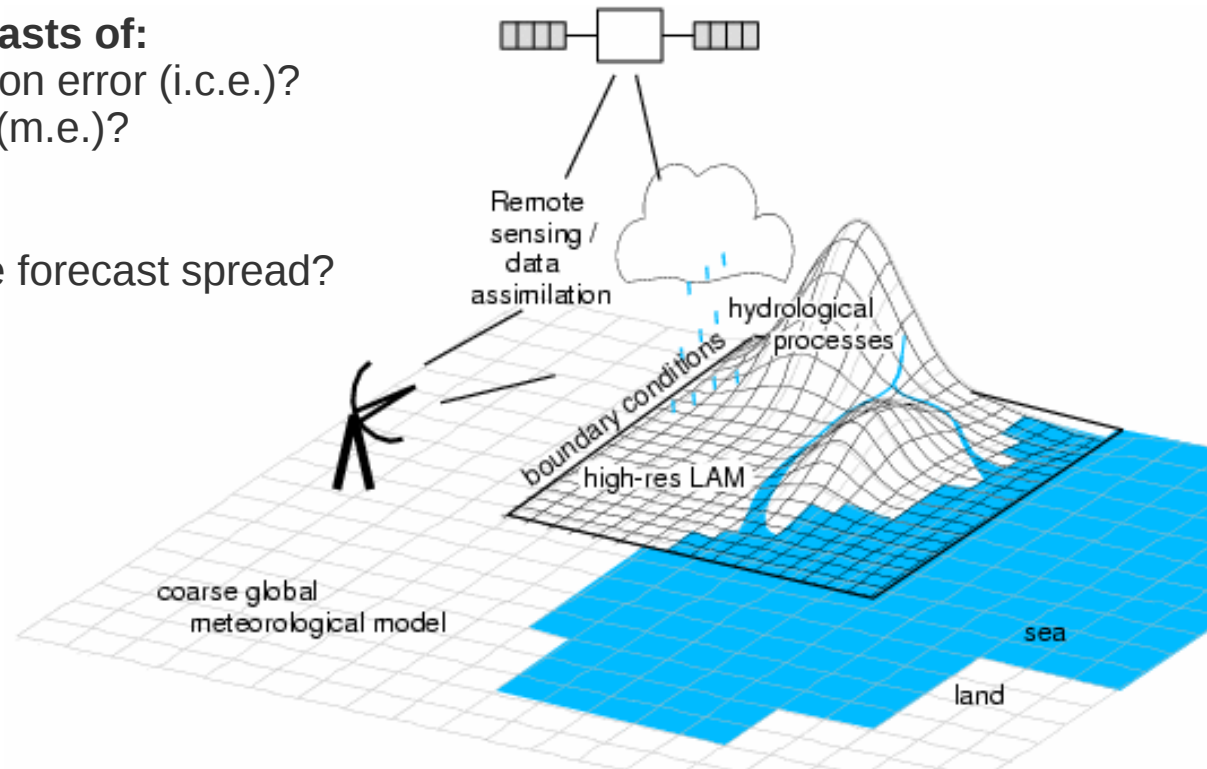
CONSTRUCTING AN ENSEMBLE

What are the respective effects on forecasts of:

- Introducing variability in the initial condition error (i.c.e.)?
- Introducing variability in the model error (m.e.)?

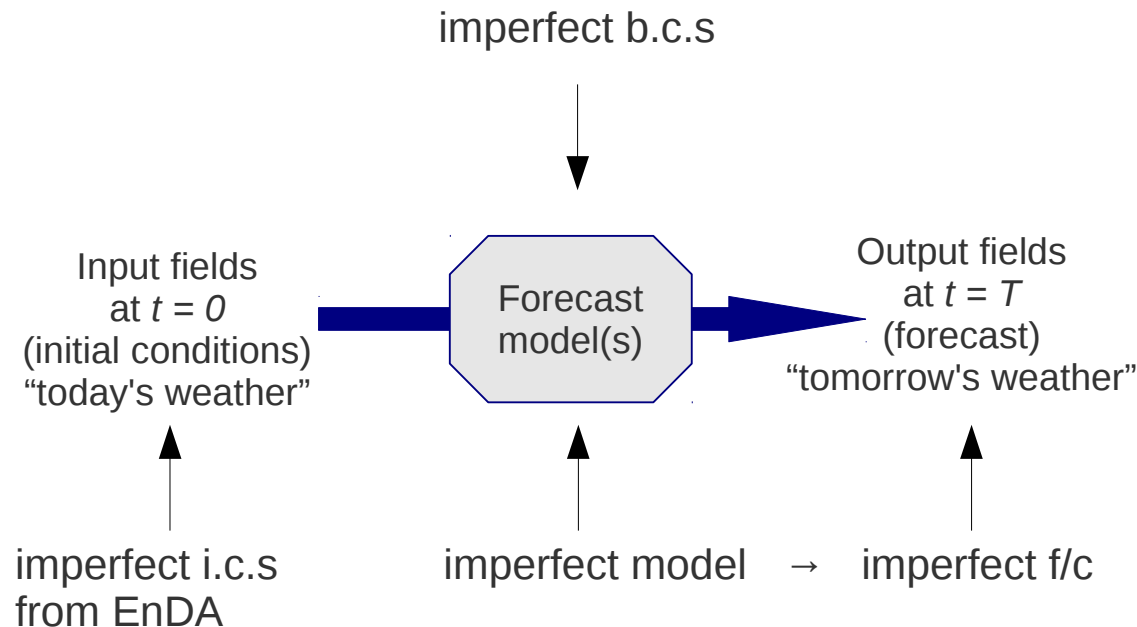
Forecast assessment and evaluation

- How does each source of error affect the forecast spread?
- How do they affect the skill?



Simulation of errors

- **Initial conditions must be chosen carefully:**
 - Each written as $x_{ic}(n) = x_0 + \delta x_{ic}(n)$, $1 \leq n \leq N$.
 - $\delta x_{ic}(n)$ must be consistent with available knowledge and its uncertainty and the behaviour of the atmosphere.
 - Initial condition uncertainty, boundary condition uncertainty, model error uncertainty..
 - If variability of $\delta x_{ic}(n)$ too small $\rightarrow$ range of possible forecasts not represented.
too large $\rightarrow$ forecasts not useful.



Ensemble prediction in the Southern UK domain

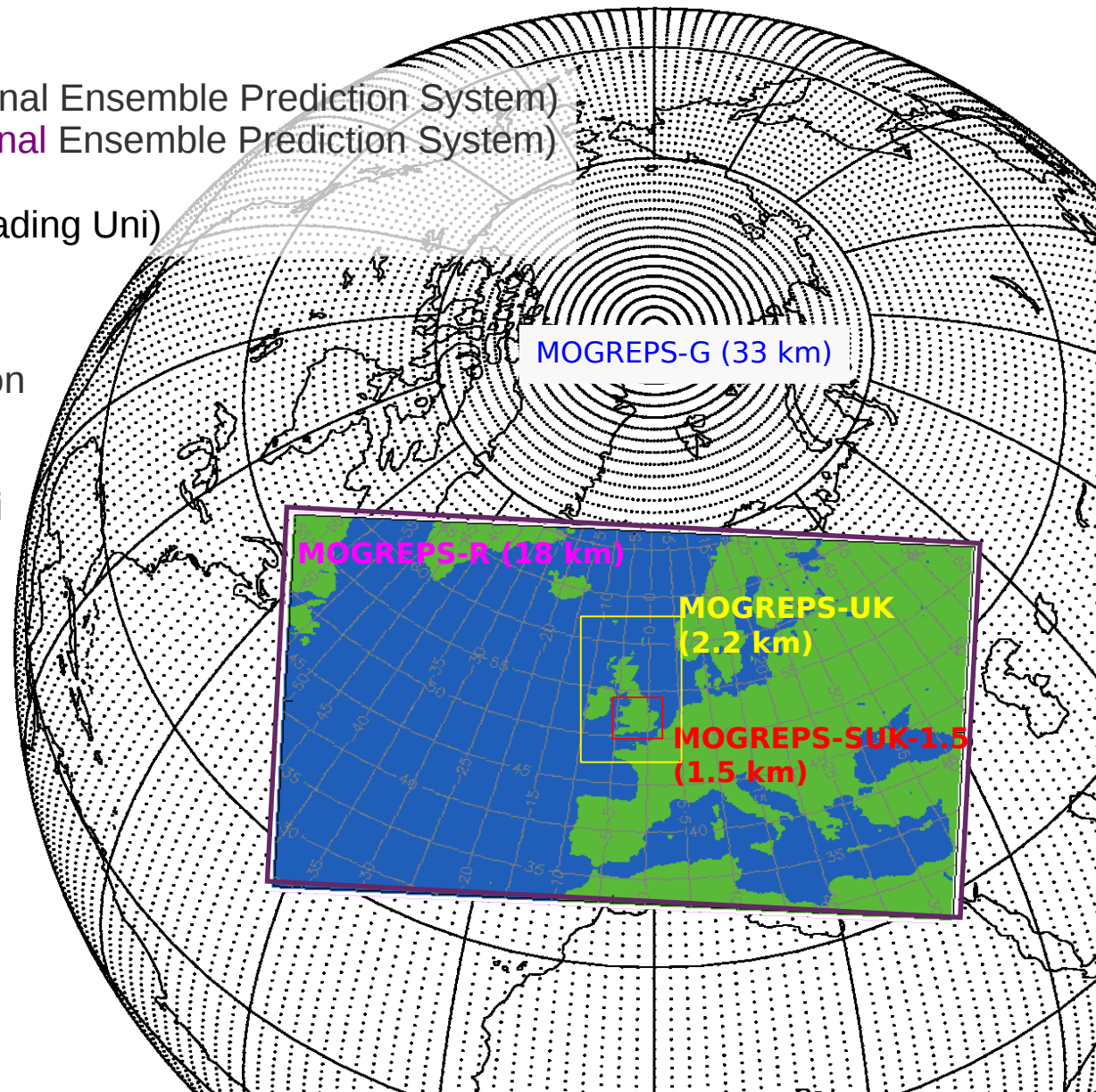
MOGREPS-**G** (Met Office **G**lobal and Regional Ensemble Prediction System)

MOGREPS-**R** (Met Office Global and **R**egional Ensemble Prediction System)

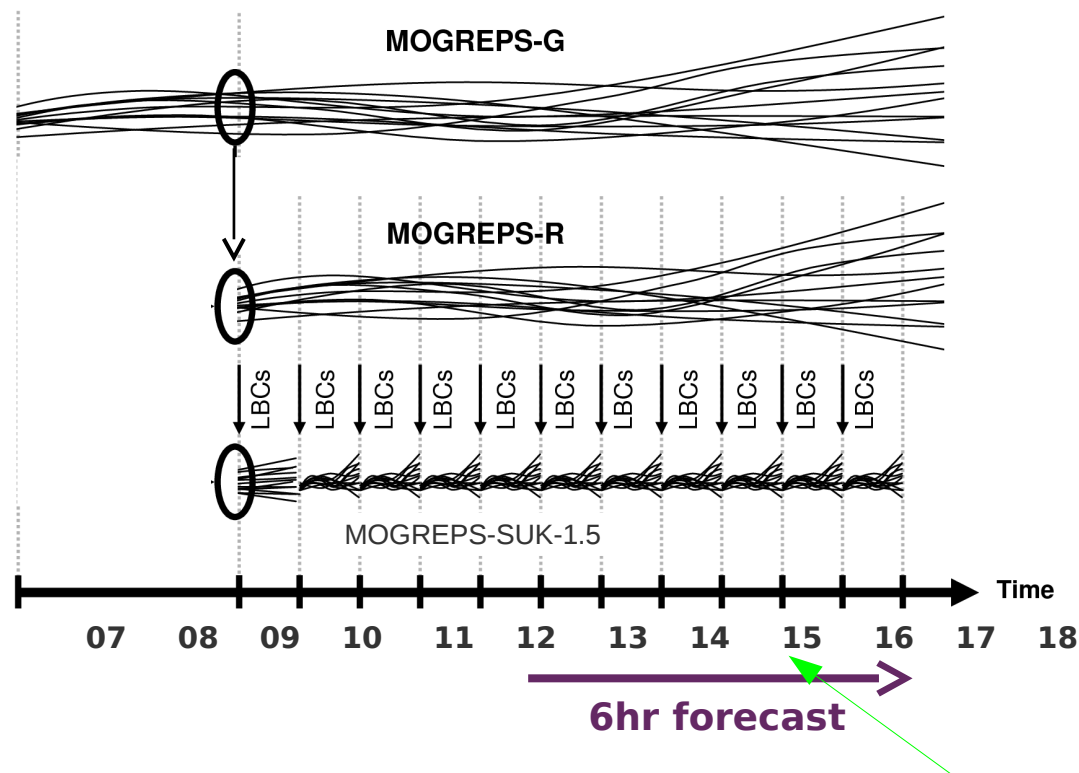
MOGREPS-**UK**

MOGREPS-**SUK-1.5** (MetO@Reading / Reading Uni)

- Determine a single set of initial condition fields by VAR.
- Add perturbations based on the a-priori ensemble and properties of the observation network used in VAR (ETKF).
- Have N sets of initial condition fields ($N=24$).
- Pass each through forecast model with (optionally) a perturbation of model parameters (the RP – random parameters – scheme).



MOGREPS-SUK-1.5 set-up

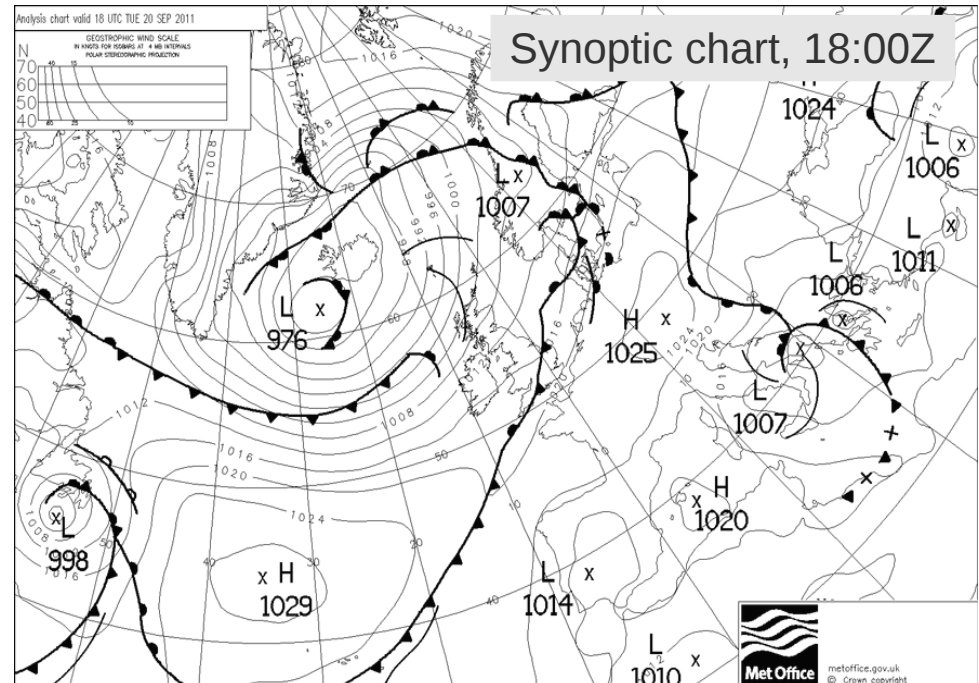
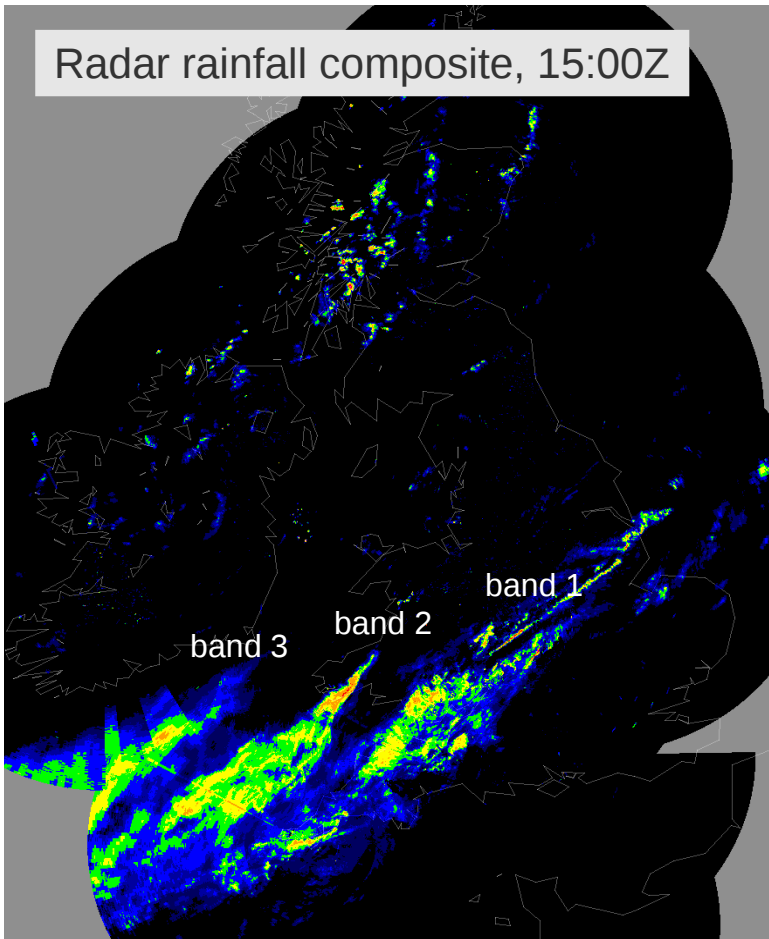


- Domain over southern UK (360 x 288 grid points)
- 1.5 km resolution grid
- Control member from 3D-Var analysis
- 23 perturbed members: initial condition perturbations and LBCs from MOGREPS-R
- Hourly-cycling ETKF for the first 6 hours
- 6 hour forecast from 12z
- Options to simulate model error variability with 'RP scheme'

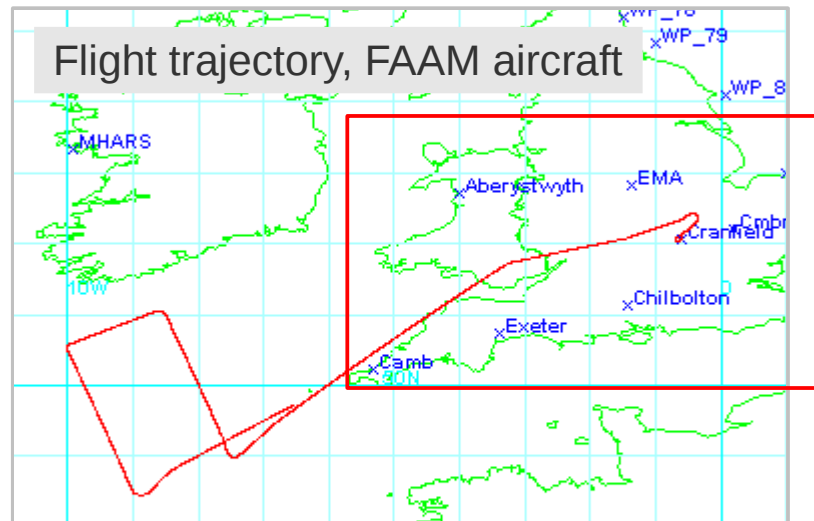
DIAMET IOP-2 case study

20/09/2011

Radar rainfall composite, 15:00Z



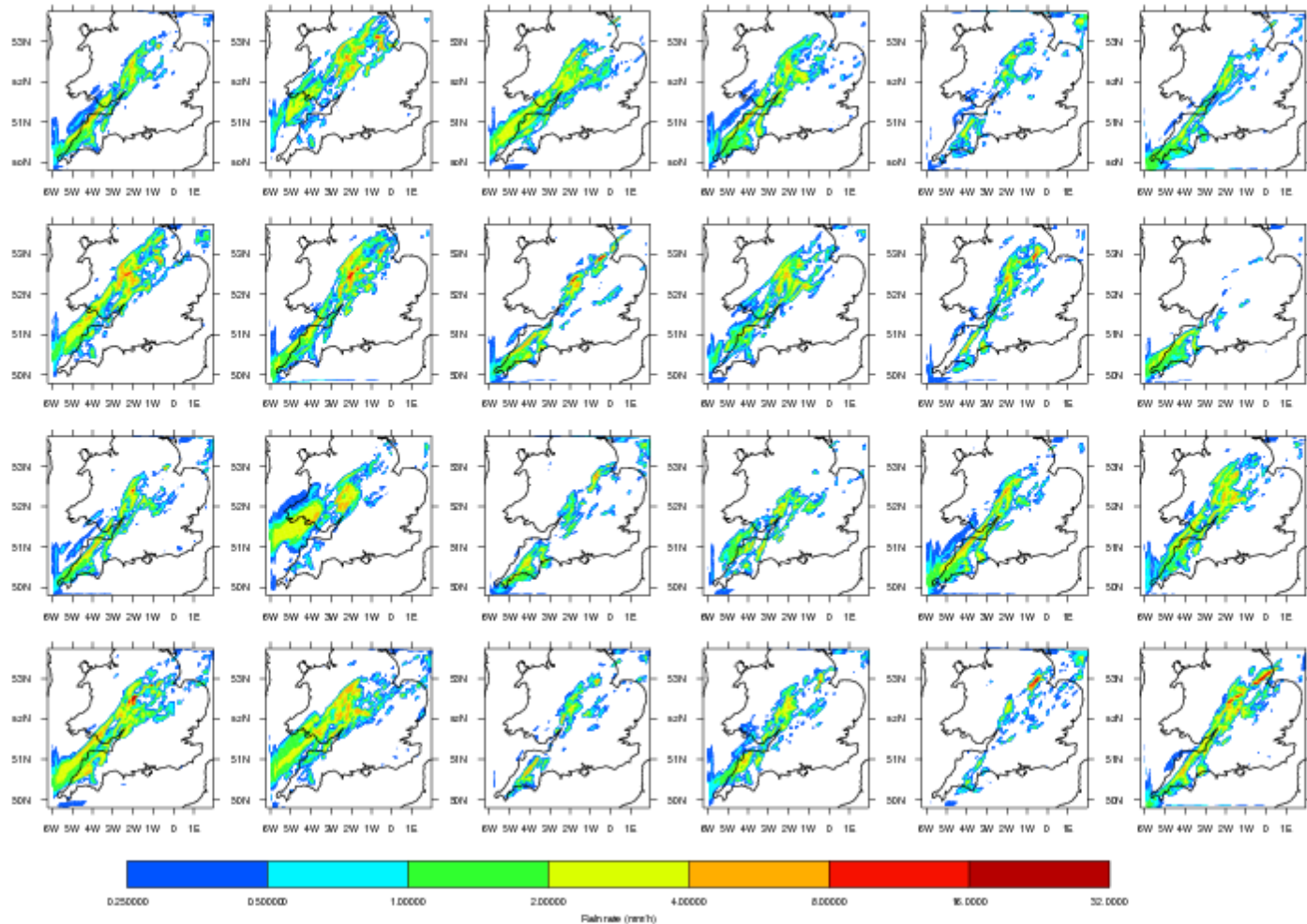
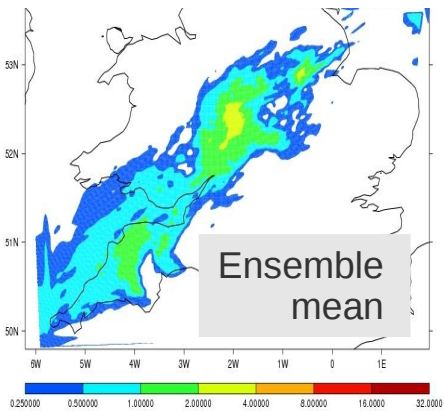
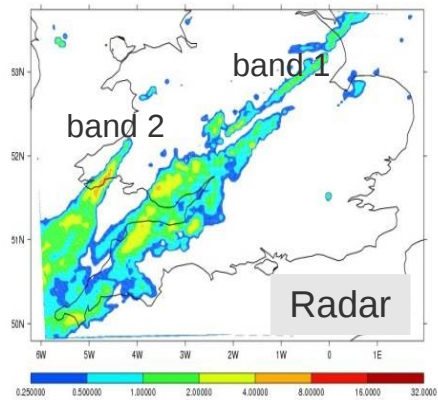
Flight trajectory, FAAM aircraft



MOGREPS-SUK-1.5 rain rate forecasts

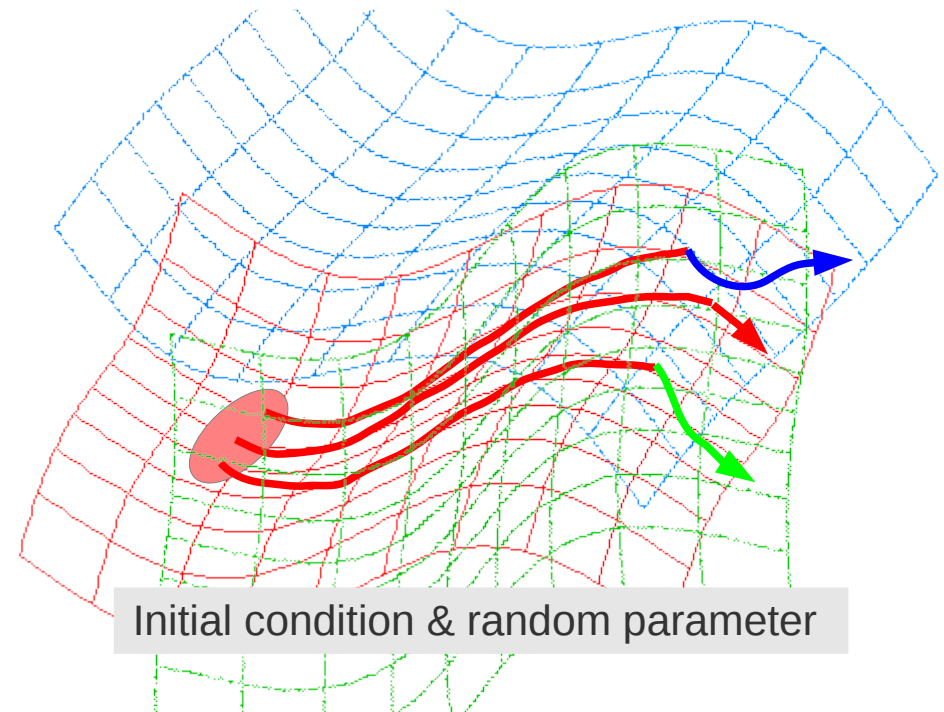
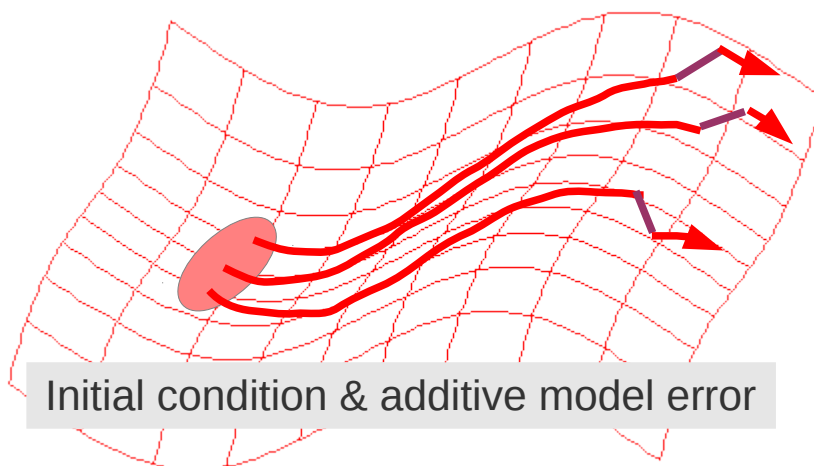
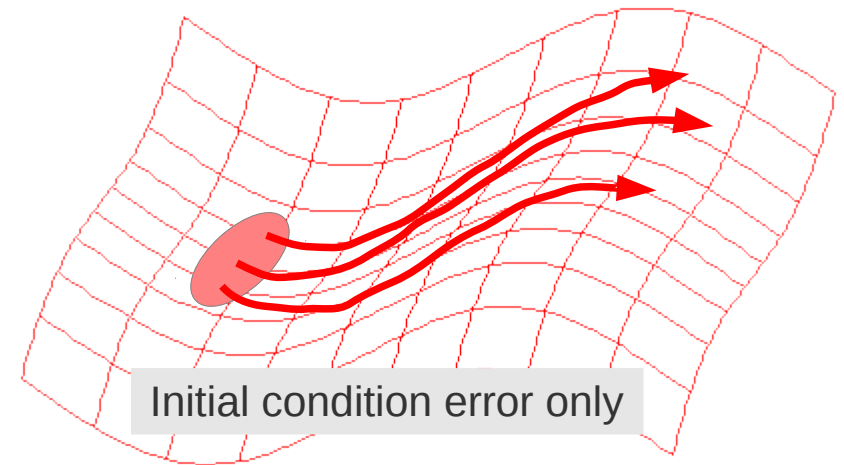
1500 UTC

CTL ensemble (i.c. variability only)



Simulating an additional source of error – model error variability

- Results on previous slides varied initial conditions only.
- Only one realisation of model error.



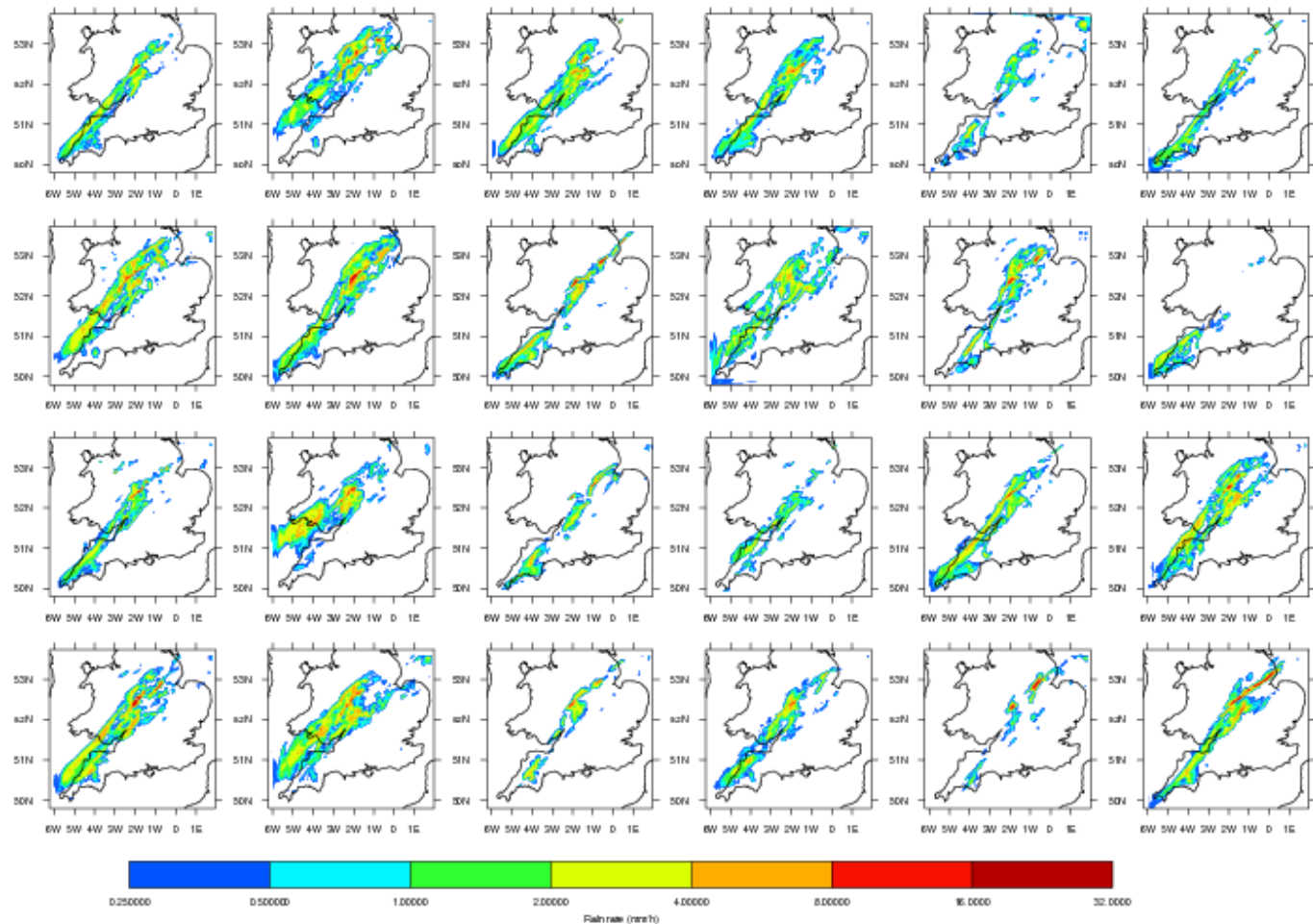
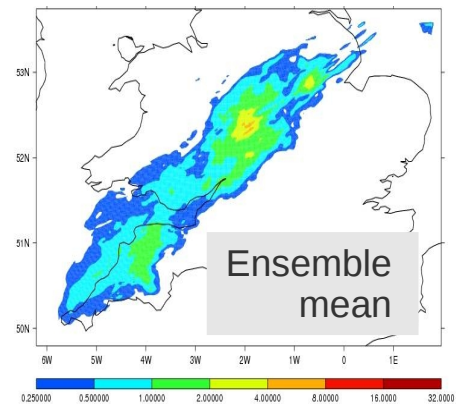
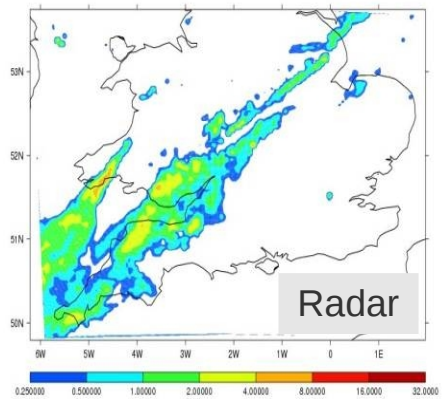
Parameters

Scheme	Parameter	Description	min	default	max
BL	g0	Flux profile parameter	5	10	20
BL	Ri _c	Critical Richardson number	0.5	1.0	2.0
BL	g _{mezcla}	Neutral mixing length	0.03	0.15	0.45
BL	λ _{min}	Minimum mixing length	8	40	120
BL	Charnock	Charnock parameter	0.010	0.011	0.026
BL	A ₁	Entrainment parameter	0.1	0.23	0.4
BL	G ₁	Cloud-top diffusion parameter	0.5	0.85	1.5
LSP	RH _{crit}	Critical relative humidity	0.875	0.9	0.910
LSP	m _{ci}	Ice-fall speed	0.3	1.0	3.0
LSP	x1r	Particle size distribution for rain	2 x 10 ⁶	8 x 10 ⁶	2 x 10 ⁹
LSP	xli	Particle size distribution for ice aggregates	1 x 10 ⁶	2 x 10 ⁶	1 x 10 ⁷
LSP	x1ic	Particle size distribution for ice crystals	2 x 10 ⁷	4 x 10 ⁷	1 x 10 ⁸
LSP	ai	Ice aggregate mass diameter	0.0222	0.0444	0.0888
LSP	aic	Ice crystal mass diameter	0.2935	0.587	1.174
LSP	t _{nuc}	Max ice nucleation temperature	-25	-10	-1
LSP	ec _{auto}	Autoconversion efficiency (converting cloud to rain)	0.01	0.55	0.6

MOGREPS-SUK-1.5 rain rate forecasts

1500 UTC

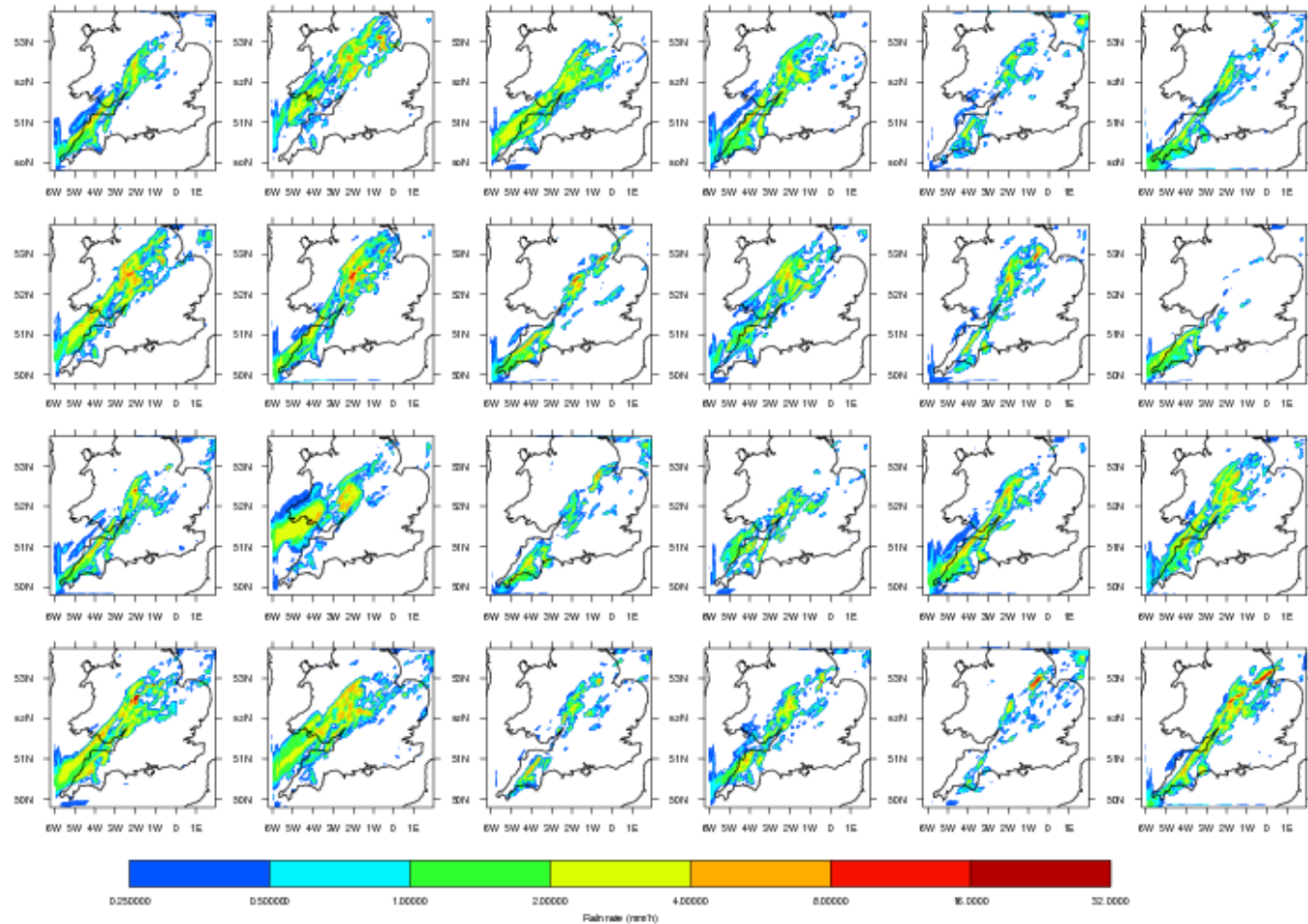
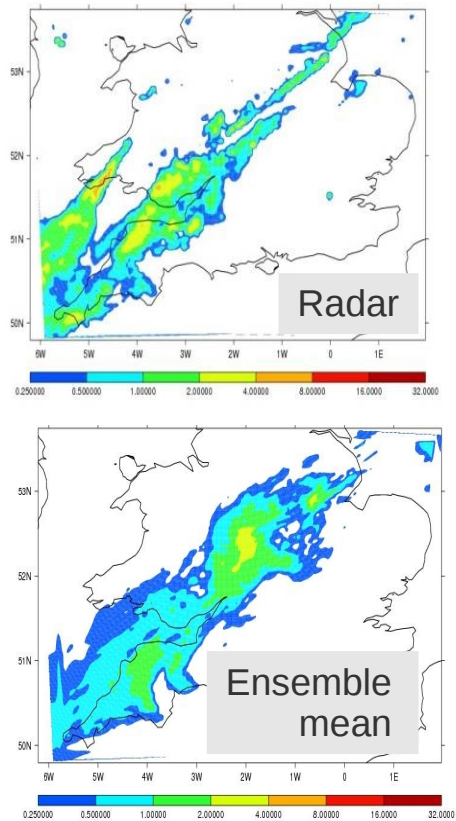
RP-fix ensemble (i.c. + fixed parameter variability)



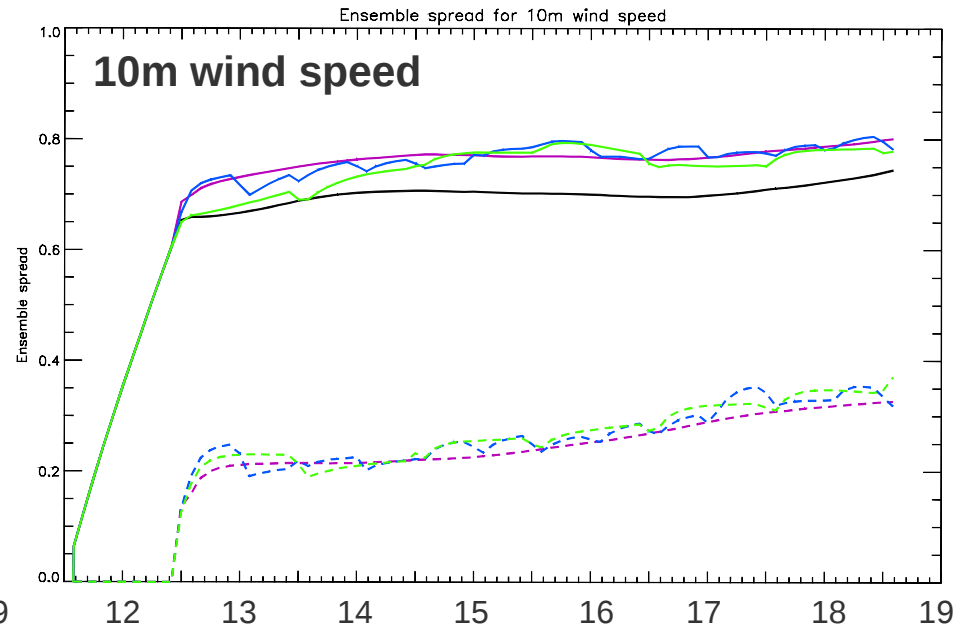
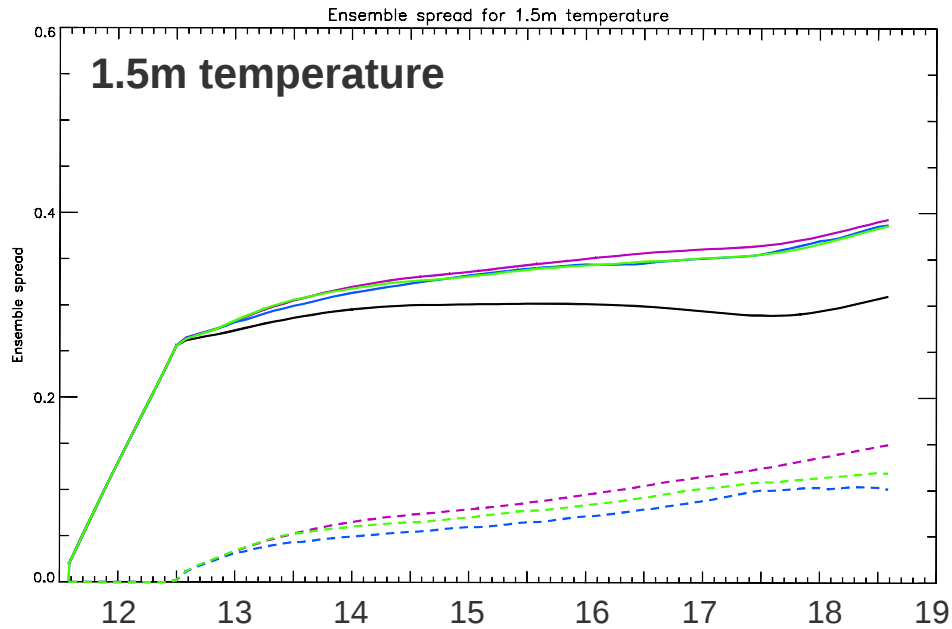
MOGREPS-SUK-1.5 rain rate forecasts

1500 UTC

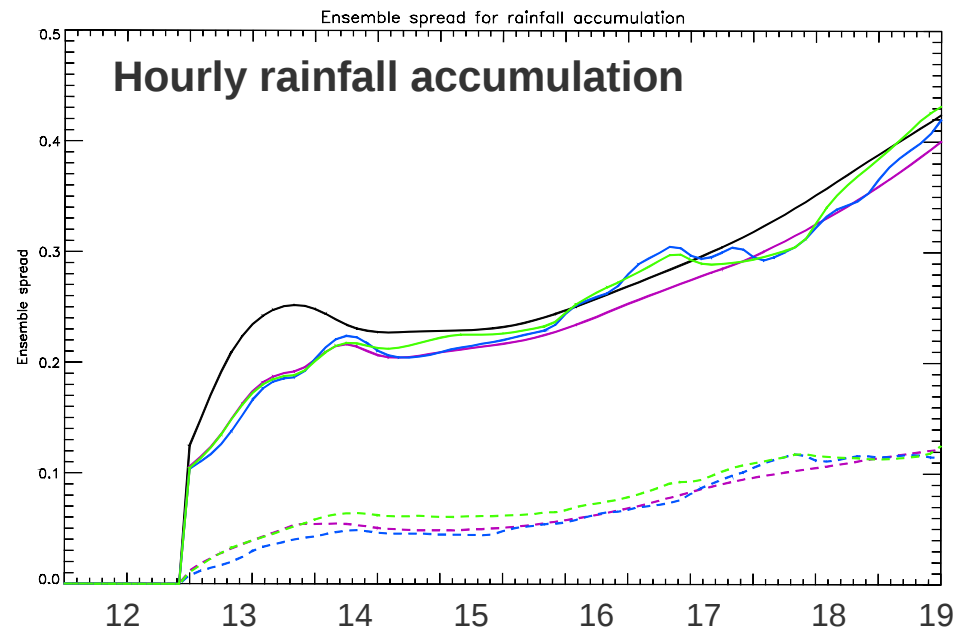
CTL ensemble (i.c. variability only)



Effect on ensemble spread



- CTL
- RP-60
- RP-30
- RP-fix
- onlyRP-60
- onlyRP-30
- onlyRP-fix



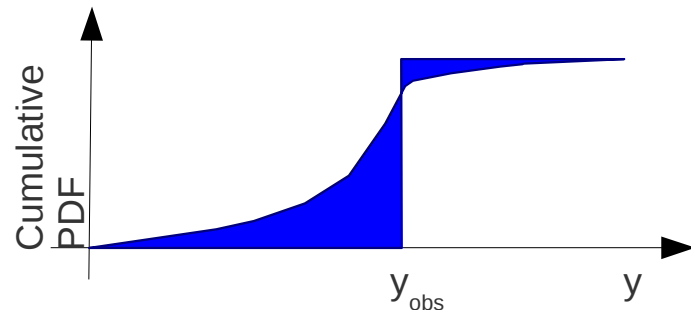
Effect on forecast skill (CRPS)

CRPS: Continuous Ranked Probability Score

$$\text{CRPS} = \int_{y=-\infty}^{+\infty} dy (C_{\text{fore}}(y) - C_{\text{obs}}(y))^2$$

$$C_{\text{fore}}(y) = \int_{y'=-\infty}^y dy' P_{\text{fore}}(y')$$

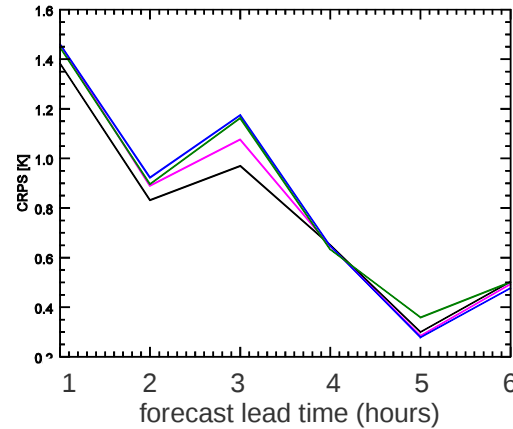
$$C_{\text{obs}}(y) = \int_{y'=-\infty}^y dy' P_{\text{fore}}(y') \\ \sim \int_{y'=-\infty}^y dy' \delta(y' - y_{\text{obs}})$$



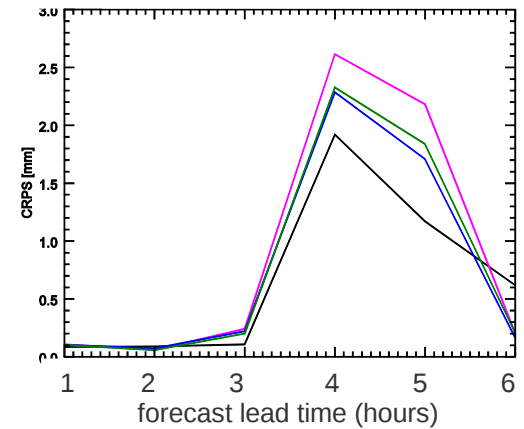
Better skill
↓

Better skill
↓

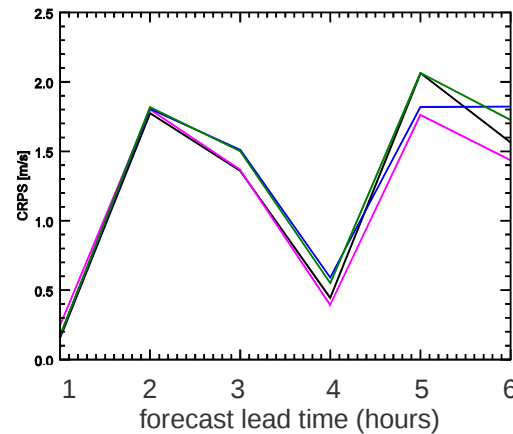
surface temperature



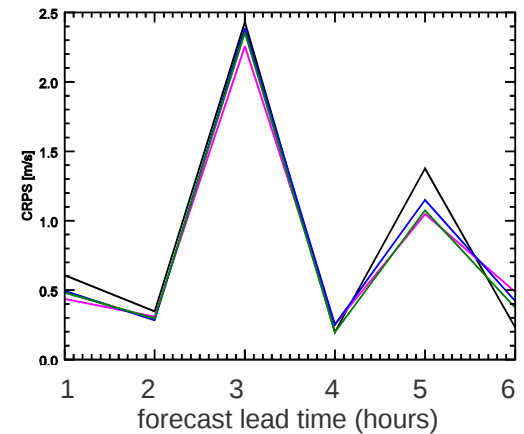
rain accumulation



u-wind component



v-wind component

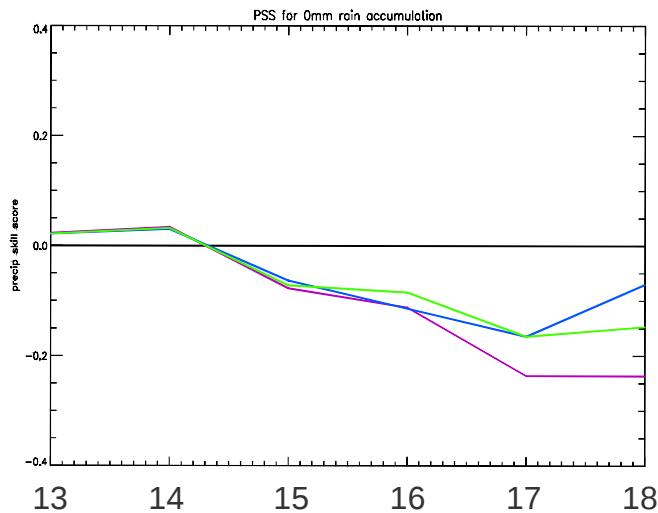


- CTL
- RP-60, RP-30, RP-fix

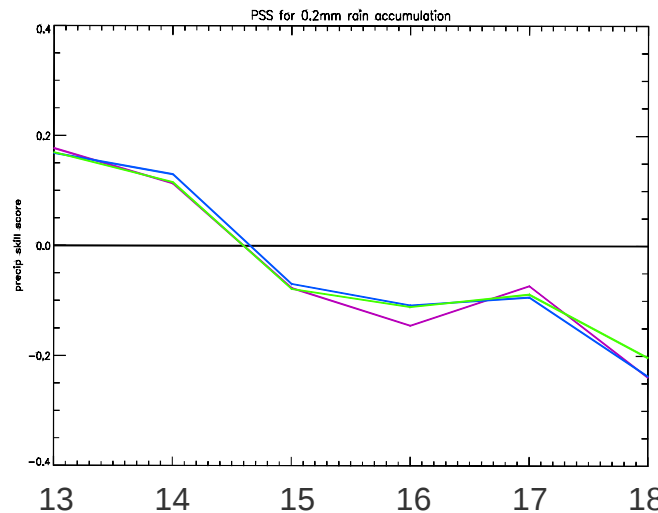
Effect on forecast skill (PSS)

Precipitation skill score for hourly rainfall accumulation

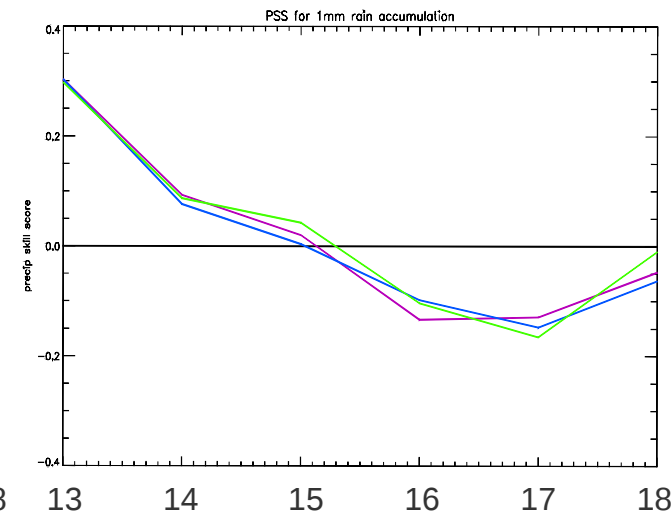
Threshold of 0 mm



Threshold of 0.2 mm



Threshold of 1.0 mm



PSS: Precipitation Skill Score

$$PSS_{\text{ens}} = 1 - \frac{BS_{\text{ens}}}{BS_{\text{ctl}}}$$

BS: Brier Score

$$BS = \frac{1}{N} \sum_{i=1}^N (P_{\text{fore}}(i) - P_{\text{obs}}(i))^2$$

$PSS_{\text{ens}} > 0$ if “ens” better than “ctl”
 $PSS_{\text{ens}} = 0$ if “ens” as good/bad as “ctl”
 $PSS_{\text{ens}} < 0$ if “ens” worse than “ctl”

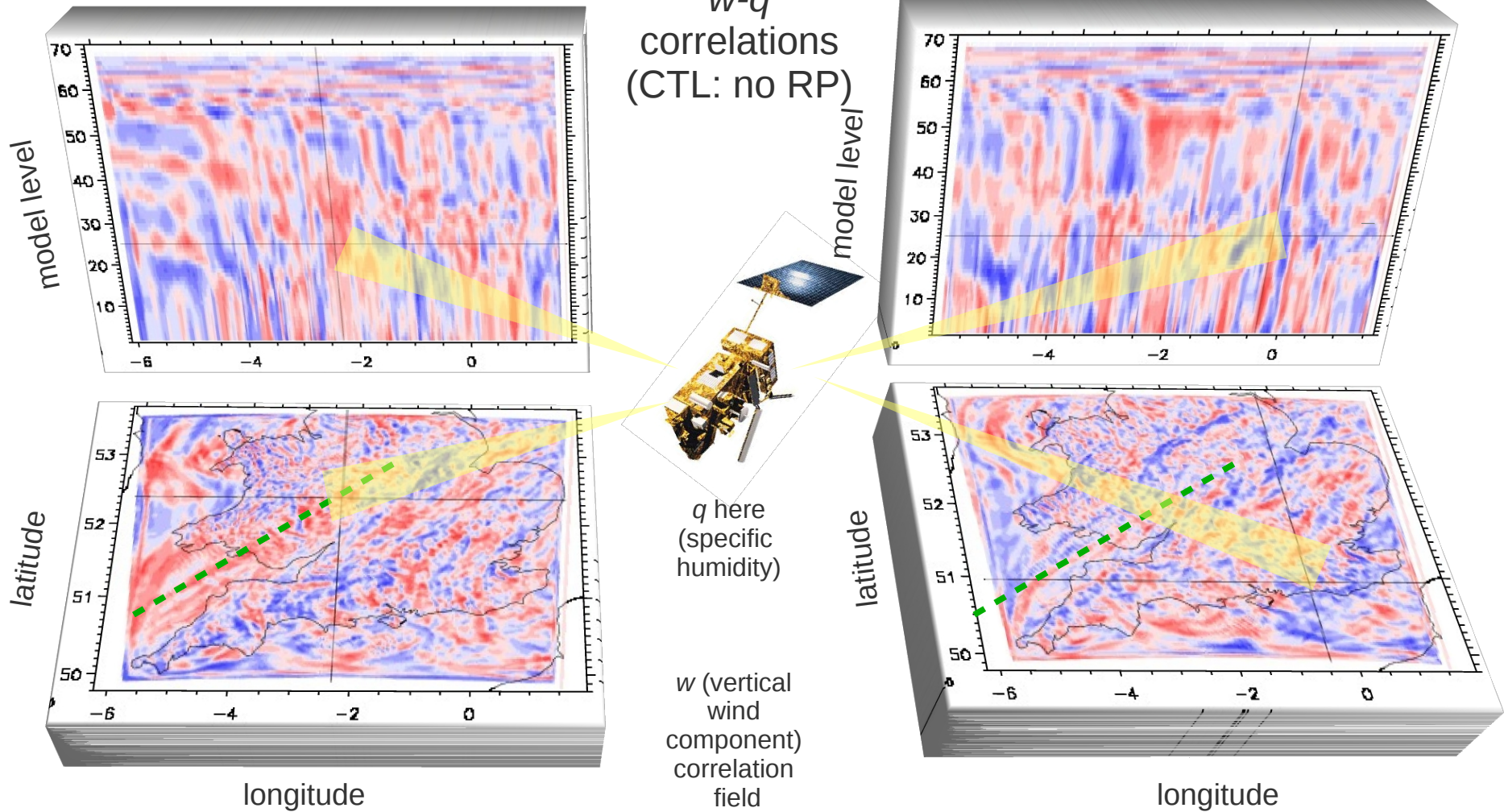
- CTL
- RP-60, RP-30, RP-fix

P_{fore} : Probability of event forecast
 P_{obs} : 1 if event observed, 0 if not

Ensemble-derived correlations (3-D)

ensemble derived

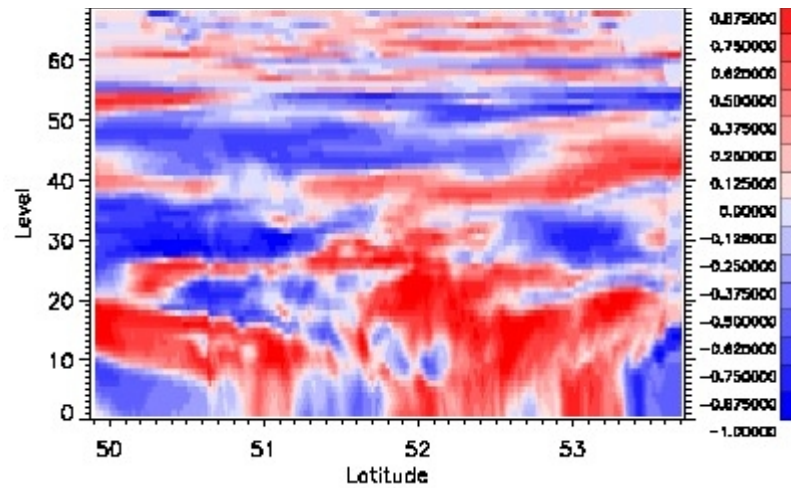
w - q
correlations
(CTL: no RP)



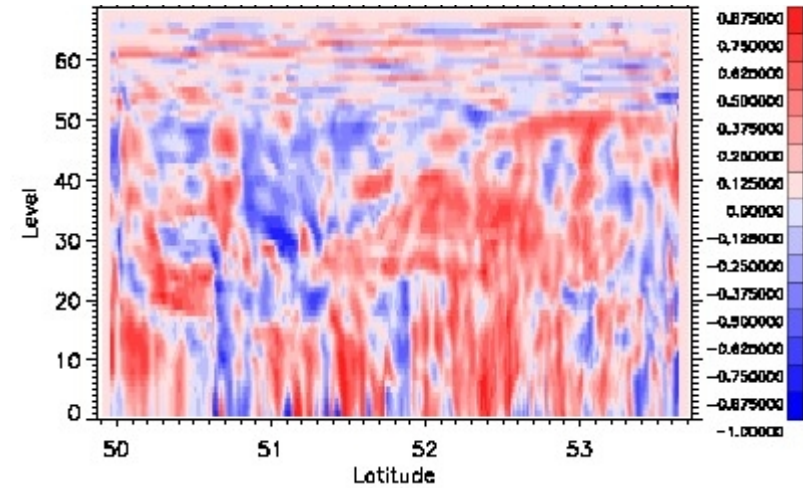
No qualitative changes with model error representation

Ensemble-derived correlations (point-by-point)

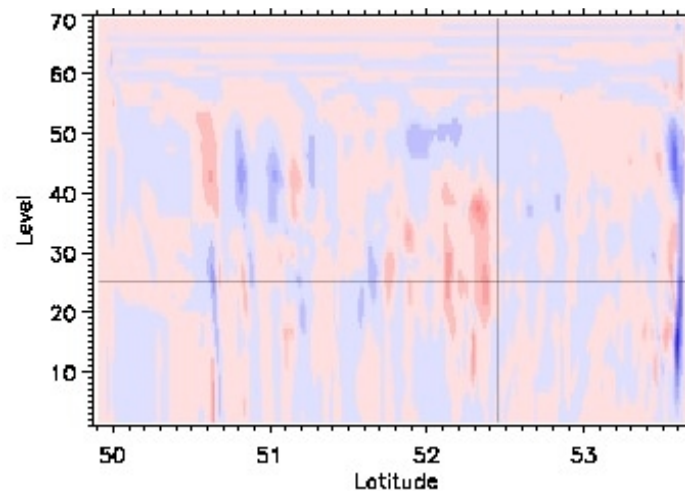
q - T correlations



q - w correlations



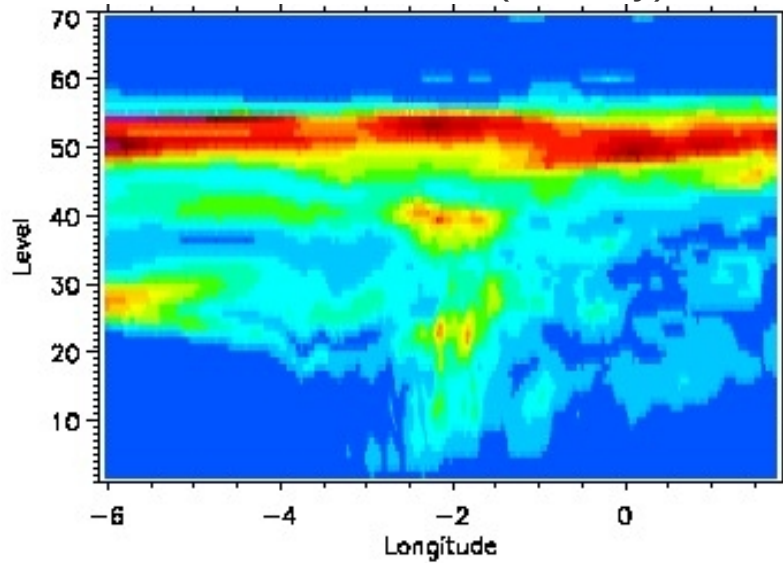
w field



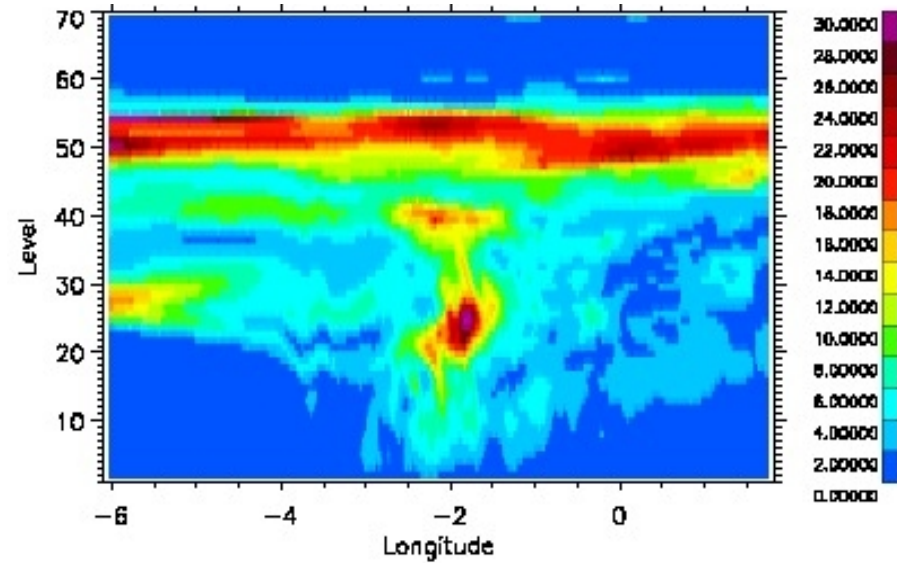
No qualitative changes with model error representation

Ensemble-derived variances (model grid)

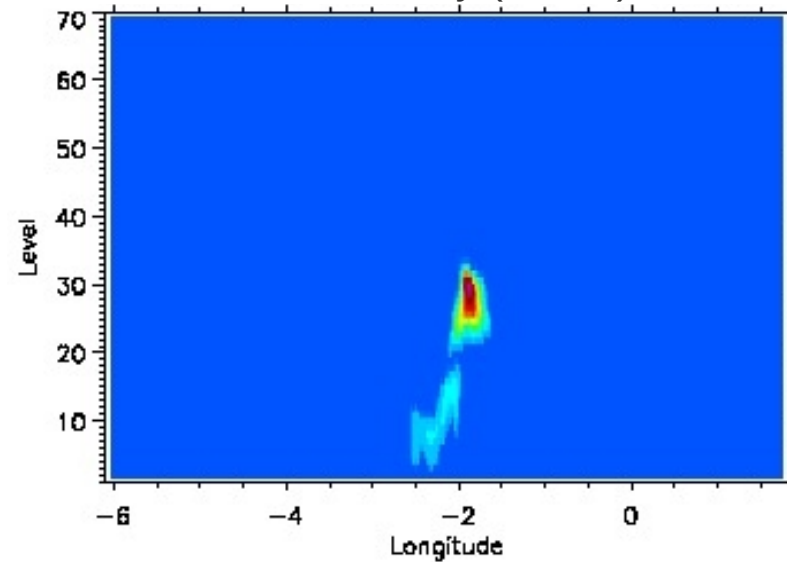
CTL: No RP (i.c. only)



Fix RP + i.c.

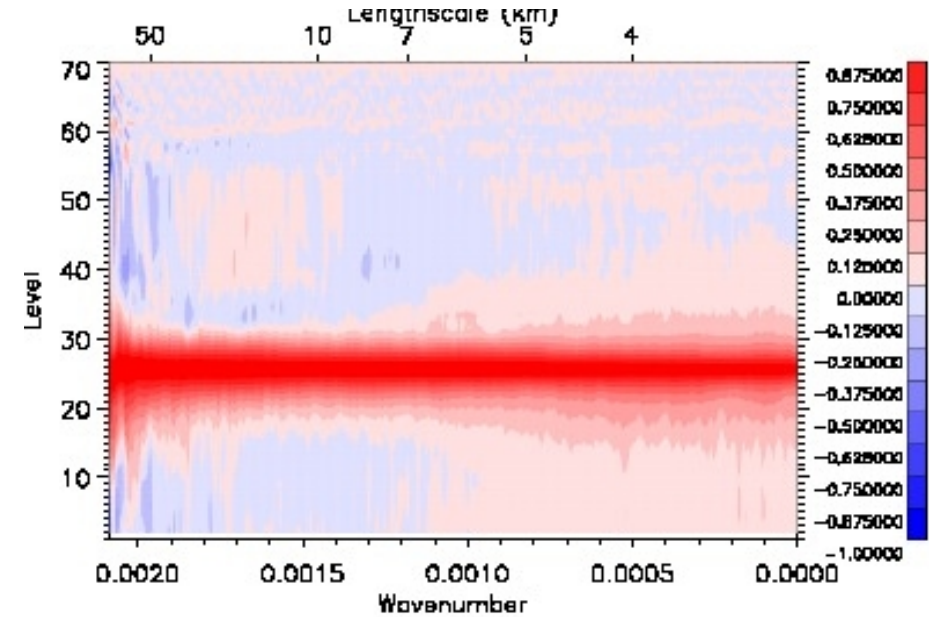
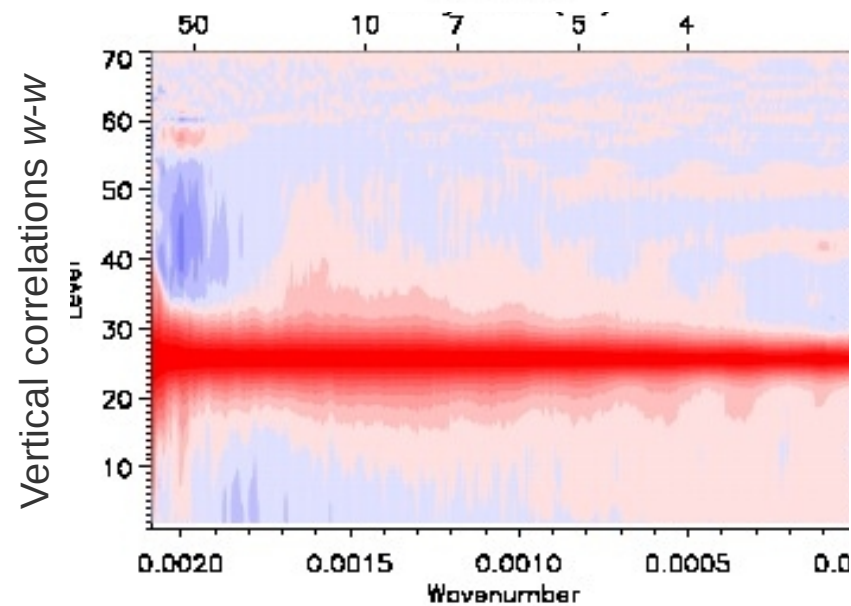
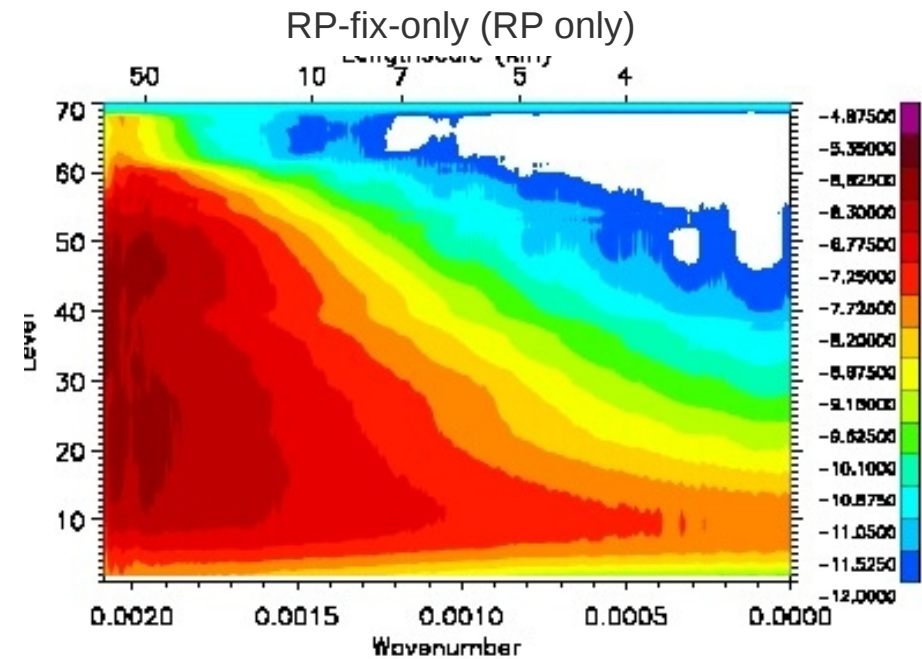
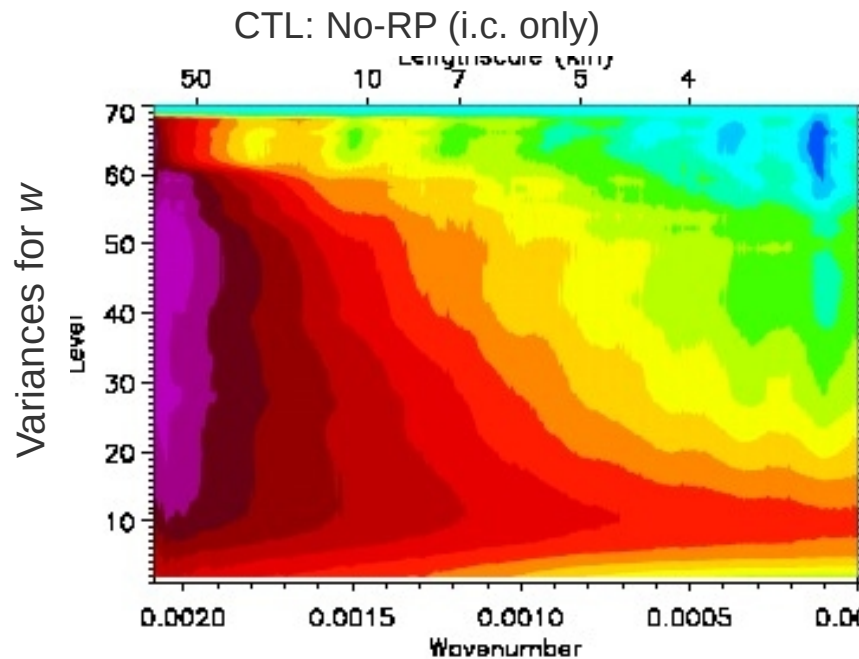


Fix RP only (no i.c.)



Wind speed variance
(m²s⁻²)

Ensemble-derived variances and correlations (spectral)



Summary

- Have run a convective-scale EPS for DIAMET IOP 2 (20/09/11) with simulation of different sources of error (*initial condition* and *model error*).
 - Central forecast initialized with 3D-VAR (operational observations).
 - Initial condition perturbations found with the *Ensemble Transform Kalman Filter*.
 - Model error variability with the *Random Parameter* scheme.
 - This is the kind of essential work that has to be done in preparation for the use of high-resolution EO data for weather forecasting.
- Cold front case with multiple banding in the cloud
 - Believe banding is real (not artefact of radar retrieval).
 - Multiple banding is evident in none of the 24-members, but some show rain in areas of both bands.
 - Forecast error covariance info essential for data assimilation. Have shown examples of how these are flow-dependent at the convective scale.
- Ensemble prediction systems generally do not have enough natural spread. Can the inclusion of model error variability help?
 - Model error shown to *increase* the spread of some quantities (T_s , $|u_s|$), but to *reduce* the spread of others (*rain rate*).
 - Model error can give variability at *small scales* and where *moist diabatic processes* are very important.
- Does the RP scheme affect skill?
 - CRPS: RP did *not improve* skill for T_s and rainfall; *neutral* for u_s , v_s .
 - BS, PSS: RP *better* skill for *first few hours*, *worse* skill *later*.
- Have/will also examine for this case:
 - Forecast sensitivity to parameters.
 - Reliability diagrams.
 - Rank histograms.
 - Innovation covariances.
 - 93-member statistics.
 - Large atlas of covariance statistics.
 - Balance properties.
 - Localization techniques.

r.n.bannister@reading.ac.uk