

## Summary of Equations - Met Office Var Scheme

1.  $\vec{w}$ -space formulation

$$\begin{aligned}
 J(\vec{w}') &= \frac{1}{2} (\vec{w}'^b - \vec{w}')^T \mathbf{B}^{-1} (\vec{w}'^b - \vec{w}') + \frac{1}{2} (\vec{y}^o - H(\vec{w}', \vec{w}^g))^T (\mathbf{E} + \mathbf{F})^{-1} (\vec{y}^o - H(\vec{w}', \vec{w}^g)) \\
 \frac{dJ}{d\vec{w}'} &= -\mathbf{B}^{-1} (\vec{w}'^b - \vec{w}') - \mathbf{H}^T (\mathbf{E} + \mathbf{F})^{-1} (\vec{y}^o - H(\vec{w}', \vec{w}^g)) \\
 \frac{d^2J_b}{d\vec{w}'^2} &= \mathbf{B}^{-1} + \mathbf{H}^T (\mathbf{E} + \mathbf{F})^{-1} \mathbf{H} \\
 \vec{w} &= \text{model state } (' \text{ pertbtn, } b \text{ backgrnd, } g \text{ guess}) \\
 H(\vec{w}', \vec{w}^g) &\approx H(\vec{w}^g) + \mathbf{H}\vec{w}' 
 \end{aligned}$$

2.  $\vec{v}$ -space formulation

$$\begin{aligned}
 \vec{v} &= \mathbf{T}\vec{w}' & \vec{w}' &= \mathbf{U}\vec{v} & \mathbf{U}^T \mathbf{B}^{-1} \mathbf{U} &= \mathbf{I} \\
 J(\vec{v}) &= \frac{1}{2} (\vec{v}^b - \vec{v})^T \mathbf{U}^T \mathbf{B}^{-1} \mathbf{U} (\vec{v}^b - \vec{v}) + \frac{1}{2} (\vec{y}^o - H(\mathbf{U}\vec{v}, \vec{w}^g))^T (\mathbf{E} + \mathbf{F})^{-1} (\vec{y}^o - H(\mathbf{U}\vec{v}, \vec{w}^g)) \\
 &= \frac{1}{2} (\vec{v}^b - \vec{v})^T (\vec{v}^b - \vec{v}) + \frac{1}{2} (\vec{y}^o - H(\mathbf{U}\vec{v}, \vec{w}^g))^T (\mathbf{E} + \mathbf{F})^{-1} (\vec{y}^o - H(\mathbf{U}\vec{v}, \vec{w}^g)) \\
 \frac{dJ}{d\vec{v}} &= -\mathbf{U}^T \mathbf{B}^{-1} \mathbf{U} (\vec{v}^b - \vec{v}) - \mathbf{U}^T \mathbf{H}^T (\mathbf{E} + \mathbf{F})^{-1} (\vec{y}^o - H(\mathbf{U}\vec{v}, \vec{w}^g)) \\
 &= (\vec{v}^b - \vec{v}) - \mathbf{U}^T \mathbf{H}^T (\mathbf{E} + \mathbf{F})^{-1} (\vec{y}^o - H(\mathbf{U}\vec{v}, \vec{w}^g)) \\
 \frac{d^2J_b}{d\vec{v}^2} &= \mathbf{U}^T \mathbf{B}^{-1} \mathbf{U} + \mathbf{U}^T \mathbf{H}^T (\mathbf{E} + \mathbf{F})^{-1} \mathbf{H} \mathbf{U} \\
 &= \mathbf{I} + \mathbf{U}^T \mathbf{H}^T (\mathbf{E} + \mathbf{F})^{-1} \mathbf{H} \mathbf{U}
 \end{aligned}$$